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The homogenization of orthorhombic piezoelectric composites by the strong-property-fluctuation theory

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Abstract

The linear strong-property-fluctuation theory (SPFT) was developed in order to estimate the constitutive parameters of certain homogenized composite materials (HCMs) in a long-wavelength regime. The component materials of the HCM were generally orthorhombic *mm2* piezoelectric materials, which were randomly distributed as oriented ellipsoidal particles. At the secondorder level of approximation, wherein a two-point correlation function and its associated correlation length characterize the component material distributions, the SPFT estimates of the HCM constitutive parameters were expressed in terms of numerically tractable two-dimensional integrals. Representative numerical calculations revealed that (i) the lowest order SPFT estimates are qualitatively similar to those provided by the corresponding Mori–Tanaka homogenization formalism, but differences between the two estimates become more pronounced as the component particles become more eccentric in shape, and (ii) the second-order SPFT estimate provides a significant correction to the lowest order estimate, which accommodates attenuation due to scattering losses.

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(Some figures in this article are in colour only in the electronic version)

1. Introduction

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The origins of the SPFT lie in wave propagation studies for continuously random media [13]. It was later adapted to estimate the electromagnetic [14-16], acoustic [17]and elastodynamic [18] constitutive parameters of HCMs. Within the SPFT, the estimation of the HCM constitutive parameters arises from the asymptotic expansion of a mass operator. The lowest order term in this expansion is represented by a homogeneous comparison medium. By a renormalization procedure, the SPFT allows for relatively strong fluctuations in the constitutive parameters describing the comparison medium and the component materials. Thus, the SPFT is distinguished from the weak-property-fluctuation theory [13]. Higher order approximations are expressed in terms of correlation functions describing the spatial distributions of the component materials. In principle, correlation functions of arbitrarily high order may be incorporated; but, in practice, the SPFT is most often implemented at the second-order level of approximation, wherein a two-point correlation function and its introduction of these spatial correlation functions, a spatially nonlocal description is achieved. As the SPFT is developed within the frequency domain, temporal nonlocality is represented by the imaginary parts of complex-valued constitutive parameters.

2. Theory

2.1. Preliminaries

In the following, we consider piezoelectric materials described by constitutive relations of the form [20, 21]

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$$\begin{aligned} \sigma_{ab} &= C_{abmn} S_{mn} - e_{nab} E_n \\ D_a &= e_{amn} S_{mn} + \epsilon_{an} E_n \end{aligned} \},$$

$$(1)$$

wherein the elastic strain S_{mn} and the electric field E_n are taken as independent variables, which are related to the stress σ_{ab} and dielectric displacement D_a via the elastic stiffness tensor C_{abmn} (measured in a constant electric field), the piezoelectric tensor e_{nab} (measured at a constant strain or electric field) and the dielectric tensor ϵ_{an} (measured at a constant strain). Here, and hereafter, tensors are represented in plain font and lowercase tensor indexes range from 1 to 3 with a repeated index implying summation.

We develop the SPFT in the frequency domain. Accordingly the complex-valued representations of the stress, strain and electromagnetic fields have an implicit $\exp(-i\omega t)$ dependence on time *t* with ω being the angular frequency and $i = \sqrt{-1}$. The possibility of dissipative behavior is thereby accommodated via the imaginary parts of complex-valued constitutive parameters.

The constitutive relations (1) are more conveniently expressed in the symbolic form

$$\breve{\sigma}_{aB} = \breve{C}_{aBMn}\breve{S}_{Mn},\tag{2}$$

where the extended stress symbol

$$\breve{\sigma}_{aB} = \begin{cases} \sigma_{ab}, & B = b = 1, 2, 3 \\ D_a, & B = 4, \end{cases}$$
(3)

the extended stiffness symbol

$$\check{C}_{aBMn} = \begin{cases} C_{abmn}, & B = b = 1, 2, 3; \ M = m = 1, 2, 3 \\ e_{nab}, & B = b = 1, 2, 3; \ M = 4 \\ -e_{amn}, & B = 4; \ M = m = 1, 2, 3 \\ \epsilon_{an}, & B, M = 4, \end{cases}$$
(4)

and the extended strain symbol

$$\check{S}_{Mn} = \begin{cases} S_{mn}, & M = m = 1, 2, 3\\ E_n, & M = 4. \end{cases}$$
(5)

Here, and hereafter, uppercase indexes range from 1 to 4. Note that the extended quantities defined in equations (3)–(5) are not tensors—these are simply symbols which are introduced to allow a compact representation of the piezoelectric constitutive relations [9].

In developing the SPFT appropriate to piezoelectric HCMs, it is expedient to express the constitutive relations (2) in a matrix vector form as³

$$\check{\boldsymbol{\sigma}} = \underline{\check{\mathbf{C}}} \cdot \check{\mathbf{S}},\tag{6}$$

$$\underline{\check{\mathbf{C}}} = \begin{pmatrix} \underline{\mathbf{C}} & -\underline{\mathbf{e}}^T \\ \underline{\mathbf{e}} & \underline{\boldsymbol{\epsilon}} \end{pmatrix},\tag{7}$$

³ This notation is an extension of the Kelvin notation [21].

where the 9 \times 9 stiffness matrix \underline{C} may be expressed as

$$\underline{\underline{\mathbf{C}}} = \begin{pmatrix} \underline{\underline{\mathbf{C}}}_{a} & \underline{\underline{\mathbf{0}}}_{3\times3} & \underline{\underline{\mathbf{0}}}_{3\times3} \\ \underline{\underline{\mathbf{0}}}_{3\times3} & \underline{\underline{\mathbf{C}}}_{b} & \underline{\underline{\mathbf{C}}}_{b} \\ \underline{\underline{\underline{\mathbf{0}}}}_{3\times3} & \underline{\underline{\mathbf{C}}}_{b} & \underline{\underline{\mathbf{C}}}_{b} \end{pmatrix},$$
(8)

with the 3×3 symmetric matrix components

$$\underline{\underline{C}}_{a} = \begin{pmatrix} C_{11} & C_{12} & C_{13} \\ C_{12} & C_{22} & C_{23} \\ C_{13} & C_{23} & C_{33} \end{pmatrix}, \qquad \underline{\underline{C}}_{b} = \begin{pmatrix} C_{44} & 0 & 0 \\ 0 & C_{55} & 0 \\ 0 & 0 & C_{66} \end{pmatrix}, \tag{9}$$

while the 9 \times 3 piezoelectric matrix **<u>e</u>** may be expressed as

$$\underline{\mathbf{e}} = \begin{pmatrix} 0 & 0 & 0 & 0 & e_{15} & 0 & 0 & e_{15} & 0 \\ 0 & 0 & 0 & e_{24} & 0 & 0 & e_{24} & 0 & 0 \\ e_{31} & e_{32} & e_{33} & 0 & 0 & 0 & 0 & 0 & 0 \end{pmatrix}$$
(10)

and the 3 \times 3 dielectric matrix $\underline{\epsilon}$ as

$$\underline{\underline{\epsilon}} = \begin{pmatrix} \epsilon_{11} & 0 & 0\\ 0 & \epsilon_{22} & 0\\ 0 & 0 & \epsilon_{33} \end{pmatrix}.$$
 (11)

The correspondence between the tensor/extended symbol representation and the matrix-vector representation is described in appendix A.

In an analogous fashion, the material density ρ may be represented via the extended density symbol

$$\breve{\rho}_{BM} = \begin{cases} \rho, & B = M = 1, 2, 3\\ 0, & \text{otherwise,} \end{cases}$$
(12)

which has the 4 \times 4 extended matrix counterpart $\underline{\check{\rho}}$ with entries

$$[\underline{\check{\rho}}]_{MP} = \breve{\rho}_{MP}.\tag{13}$$

2.2. Component materials

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$$\mathbf{r}^{(e)} = \eta \underline{\mathbf{U}} \cdot \hat{\mathbf{r}},\tag{14}$$



Figure 1. A schematic illustration of a random mixture of two different populations of ellipsoidal particles, sharing the same orientation.

where η is a linear measure of size, $\hat{\mathbf{r}}$ is the radial unit vector and the diagonal shape matrix

$$\underline{\underline{U}} = \frac{1}{\sqrt[3]{abc}} \begin{pmatrix} a & 0 & 0\\ 0 & b & 0\\ 0 & 0 & c \end{pmatrix} \qquad (a, b, c \in \mathbb{R}^+).$$
(15)

$$\Phi^{(\ell)}(\mathbf{r}) = \begin{cases} 1, & \mathbf{r} \in V^{(\ell)} \\ 0, & \mathbf{r} \notin V^{(\ell)} \end{cases} \quad (\ell = 1, 2).$$
(16)

The ensemble average of $\Phi^{(\ell)}$, i.e.,

$$\langle \Phi^{(\ell)}(\mathbf{r}) \rangle = f^{(\ell)} \qquad (\ell = 1, 2), \tag{17}$$

$$\langle \Phi^{(\ell)}(\mathbf{r})\Phi^{(\ell)}(\mathbf{r}')\rangle = \begin{cases} \langle \Phi^{(\ell)}(\mathbf{r})\rangle\langle \Phi^{(\ell)}(\mathbf{r}')\rangle, & |\underline{\underline{U}}^{-1}\cdot(\mathbf{r}-\mathbf{r}')| > L\\ \langle \Phi^{(\ell)}(\mathbf{r})\rangle, & |\underline{\underline{U}}^{-1}\cdot(\mathbf{r}-\mathbf{r}')| \leqslant L, \end{cases}$$
(18)

2.3. Comparison material

In order to establish the spectral Green function for the OCM—which is a key element in the SPFT formulation—we first consider the corresponding extended equation of motion. This may be written in the frequency domain as [28]

$$\check{C}^{(\rm OCM)}_{lMPa}\partial_l\partial_q\check{u}_P + \omega^2\check{u}_M = -\check{F}_M,\tag{19}$$

where the extended displacement

$$\check{u}_M = \begin{cases}
u_m, & M = m = 1, 2, 3 \\
\Phi, & P = 4
\end{cases}$$
(20)

combines the displacement u_m and electric scalar potential Φ , and the extended body force

$$\breve{F}_M = \begin{cases} F_m, & M = m = 1, 2, 3\\ -q, & M = 4 \end{cases}$$
(21)

combines the body force F_m and the electric charge q. Following the approach of Zhuck and Lakhtakia [18], the spatial Fourier transformation of equation (19) yields the sought after spectral Green function for the OCM as the 4 × 4 matrix:

$$\underline{\underline{\mathbf{G}}}^{(\text{OCM})}(\mathbf{k}) = [k^2 \underline{\underline{\mathbf{a}}}(\hat{\mathbf{k}}) - \omega^2 \underline{\check{\underline{\boldsymbol{\rho}}}}^{(\text{OCM})}]^{-1}.$$
(22)

Herein, the 4 \times 4 matrix $\underline{\mathbf{a}}(\hat{\mathbf{k}})$ has entries

$$[\underline{\underline{\mathbf{a}}}(\hat{\mathbf{k}})]_{MP} = \frac{k_s \check{C}_{sMPq}^{(\mathrm{OCM})} k_q}{k^2},\tag{23}$$

while $\mathbf{k} = k\hat{\mathbf{k}} \equiv (k_1, k_2, k_3)$ with $\hat{\mathbf{k}} = (\sin\theta\cos\phi, \sin\theta\sin\phi, \cos\theta)$.

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$$\left(\Phi^{(1)}(\mathbf{r})\xi_{lMPq}^{(1)} + \Phi^{(2)}(\mathbf{r})\xi_{lMPq}^{(2)}\right) = 0,$$
(24)

$$\langle \Phi^{(1)}(\mathbf{r})[\check{\rho}^{(1)} - \check{\rho}^{(\text{OCM})}]_{MP} + \Phi^{(2)}(\mathbf{r})[\check{\rho}^{(2)} - \check{\rho}^{(\text{OCM})}]_{MP} \rangle = 0$$
(25)

are imposed. We note that equation (24) is, in fact, the Bruggeman equation, which has been widely used in electromagnetics for the past 70 years [29]. In equation (24), the quantities

$$\xi_{lMPq}^{(\ell)} = \left(\check{C}_{lMSt}^{(\ell)} - \check{C}_{lMSt}^{(\text{OCM})}\right) \eta_{StPq}^{(\ell)} \qquad (\ell = 1, 2),$$
(26)

where $\eta_{StPq}^{(\ell)}$ is given implicitly through

$$\check{S}_{Pq}^{(\ell)} = \eta_{PqSt}^{(\ell)} f_{St}^{(\ell)}, \tag{27}$$

$$f_{Tj}^{(\ell)} = \check{S}_{Tj}^{(\ell)} + W_{TjlM} \big(\check{C}_{lMPq}^{(\ell)} - \check{C}_{lMPq}^{(\text{OCM})} \big) \check{S}_{Pq}^{(\ell)}$$

$$\tag{28}$$

with the renormalization tensor

$$W_{PstU} = \begin{cases} \frac{1}{8\pi} \int_{0}^{2\pi} \mathrm{d}\phi \int_{0}^{\pi} \mathrm{d}\theta \, \frac{\sin\theta}{(\underline{\underline{U}}^{-1} \cdot \hat{\mathbf{k}}) \cdot (\underline{\underline{U}}^{-1} \cdot \hat{\mathbf{k}})} \\ \times (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})_{t} \{ (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})_{s} [\underline{\underline{a}}^{-1} (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})]_{pU} \\ + (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})_{p} [\underline{\underline{a}}^{-1} (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})]_{sU} \}, \qquad P = p = 1, 2, 3 \\ \frac{1}{8\pi} \int_{0}^{2\pi} \mathrm{d}\phi \int_{0}^{\pi} \mathrm{d}\theta \sin\theta \, \frac{(\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})_{t} (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})_{s} [\underline{\underline{a}}^{-1} (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}})]_{pU}} \\ (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}}) \cdot (\underline{\underline{\underline{U}}}^{-1} \cdot \hat{\mathbf{k}}) - P = 4. \end{cases}$$

$$(29)$$

$$f^{(1)}[(\underline{\breve{\mathbf{C}}}^{(1)} - \underline{\breve{\mathbf{C}}}^{(\text{OCM})})^{\dagger} + \underline{\mathbf{W}}]^{\dagger} + f^{(2)}[(\underline{\breve{\mathbf{C}}}^{(2)} - \underline{\breve{\mathbf{C}}}^{(\text{OCM})})^{\dagger} + \underline{\mathbf{W}}]^{\dagger} = \underline{\mathbf{0}}_{12 \times 12}, \quad (30)$$

wherein the 12 × 12 matrix equivalent of W_{RstU} (namely, $\underline{\mathbf{W}}$) has been introduced and [†] denotes the matrix operation defined in appendix A. The OCM stiffness matrix may be extracted from (30) as

$$\underline{\underline{\breve{C}}}^{(\text{OCM})} = \underline{\underline{\breve{C}}}^{(1)} + f^{(2)}[\underline{\underline{\tau}} + (\underline{\underline{\breve{C}}}^{(2)} - \underline{\underline{\breve{C}}}^{(\text{OCM})}) \cdot \underline{\underline{W}}]^{\dagger} \cdot (\underline{\underline{\breve{C}}}^{(1)} - \underline{\underline{\breve{C}}}^{(2)}), \tag{31}$$

After combining equation (17) with equation (25), it follows immediately that the OCM density is the volume average of the densities of the component materials '1' and '2'; i.e.,

$$\underline{\check{\rho}}_{\underline{\underline{\rho}}}^{(\text{OCM})} = f^{(1)} \underline{\check{\rho}}_{\underline{\underline{\rho}}}^{(1)} + f^{(2)} \underline{\check{\rho}}_{\underline{\underline{\rho}}}^{(2)}.$$
(32)

2.4. Second-order SPFT

$$\check{C}_{lMPq}^{(\text{SPFT})} = \check{C}_{lMPq}^{(\text{OCM})} - \frac{\omega^2}{2} \int d^3k \, \frac{k_t}{k^2} B_{tUPq}^{lMrs}(\mathbf{k}) [\check{\underline{\rho}}_{\underline{=}}^{(\text{OCM})}]_{XY} [\underline{\underline{G}}^{(\text{OCM})}(\mathbf{k})]_{YU} \\
\times \{k_s[\underline{\underline{a}}^{-1}(\hat{\mathbf{k}})]_{rX} + k_r[\underline{\underline{a}}^{-1}(\hat{\mathbf{k}})]_{sX}\} \\
- \frac{\omega^2}{2} \int d^3k \, \frac{k_t}{k^2} B_{tUPq}^{lM4s}(\mathbf{k}) [\check{\underline{\rho}}^{(\text{OCM})}]_{XY} [\underline{\underline{G}}^{(\text{OCM})}(\mathbf{k})]_{YU} \{k_s[\underline{\underline{a}}^{-1}(\hat{\mathbf{k}})]_{4X}\}$$
(33)

and

as

$$\check{\rho}_{MP}^{(\text{SPFT})} = \check{\rho}_{MP}^{(\text{OCM})} + \omega^2 \int d^3k \ B_{MSUP}(\mathbf{k}) [\underline{\underline{\mathbf{G}}}^{(\text{OCM})}(\mathbf{k})]_{SU}.$$
(34)

The symbols $B_{tUPq}^{lMRs}(\mathbf{k})$ and $B_{MSUP}(\mathbf{k})$ represent the spectral covariance functions given

$$B_{tUPq}^{IMNs}(\mathbf{k}) = \frac{\left(\xi_{IMNs}^{(2)} - \xi_{IMNs}^{(1)}\right)\left(\xi_{tUPq}^{(2)} - \xi_{tUPq}^{(1)}\right)}{8\pi^{3}} \int d^{3}R \,\Gamma(\mathbf{R}) \exp(-i\mathbf{k} \cdot \mathbf{R}) \\ B_{MSUP}(\mathbf{k}) = \frac{\left(\check{\rho}_{MS}^{(2)} - \check{\rho}_{MS}^{(1)}\right)\left(\check{\rho}_{UP}^{(2)} - \check{\rho}_{UP}^{(1)}\right)}{8\pi^{3}} \int d^{3}R \,\Gamma(\mathbf{R}) \exp(-i\mathbf{k} \cdot \mathbf{R})$$

with

$$\Gamma(\mathbf{R}) = \Gamma(\mathbf{r} - \mathbf{r}') = \langle \Phi^{(1)}(\mathbf{r})\Phi^{(1)}(\mathbf{r}')\rangle - \langle \Phi^{(1)}(\mathbf{r})\rangle\langle \Phi^{(1)}(\mathbf{r}')\rangle \equiv \langle \Phi^{(2)}(\mathbf{r})\Phi^{(2)}(\mathbf{r}')\rangle - \langle \Phi^{(2)}(\mathbf{r})\rangle\langle \Phi^{(2)}(\mathbf{r}')\rangle.$$
(36)

$$\int d^3 R \,\Gamma(\mathbf{R}) \exp(-i\mathbf{k} \cdot \mathbf{R}) = \int_{|\mathbf{R}| \leq L} d^3 R \exp[-i(\underline{\underline{\mathbf{U}}} \cdot \mathbf{k}) \cdot \mathbf{R}].$$
(37)

Thereby, the expressions for $B_{tUPq}^{lMRs}(\mathbf{k})$ and $B_{MSUP}(\mathbf{k})$ reduce to

$$B_{tUPq}^{IMRs}(\mathbf{k}) = \frac{f^{(1)}f^{(2)}(\xi_{lMRs}^{(2)} - \xi_{lMRs}^{(1)})(\xi_{tUPq}^{(2)} - \xi_{tUPq}^{(1)})}{2(\pi k\sigma)^2} \left[\frac{\sin(k\sigma L)}{k\sigma} - L\cos(k\sigma L)\right] \\ B_{MSUP}(\mathbf{k}) = \frac{f^{(1)}f^{(2)}(\check{\rho}_{MS}^{(2)} - \check{\rho}_{MS}^{(1)})(\check{\rho}_{UP}^{(2)} - \check{\rho}_{UP}^{(1)})}{2(\pi k\sigma)^2} \left[\frac{\sin(k\sigma L)}{k\sigma} - L\cos(k\sigma L)\right] \\ \end{cases}, \quad (38)$$

wherein the scalar function

$$\sigma \equiv \sigma(\theta, \phi) = \sqrt{a^2 \sin^2 \theta \cos^2 \phi + b^2 \sin^2 \theta \sin^2 \phi + c^2 \cos^2 \theta}$$
(39)

is introduced.

$$\underline{\underline{G}}^{(\text{OCM})}(\mathbf{k}) = \frac{\underline{\underline{D}}(\mathbf{k})}{\underline{\underline{\Delta}}(\mathbf{k})},\tag{40}$$

where the 4×4 matrix function

$$\underline{\underline{\mathbf{D}}}(\mathbf{k}) = \operatorname{adj}[k^2 \underline{\underline{\mathbf{a}}}(\hat{\mathbf{k}}) - \omega^2 \underbrace{\underline{\check{\mathbf{p}}}}_{\equiv}^{(\operatorname{OCM})}]$$
(41)

and the scalar function

$$\Delta(k) = k^{8} \operatorname{det}[\underline{\underline{a}}(\hat{\mathbf{k}})] - \operatorname{tr}\{\operatorname{adj}[k^{2}\underline{\underline{a}}(\hat{\mathbf{k}})] \cdot \omega^{2} \underline{\check{\rho}}^{(\operatorname{OCM})}\} - k^{2} \operatorname{tr}[\operatorname{adj}(\omega^{2} \underline{\check{\rho}}^{(\operatorname{OCM})}) \cdot \underline{\underline{a}}(\hat{\mathbf{k}})] + k^{4} (\operatorname{tr}\{[\underline{\underline{a}}(\hat{\mathbf{k}})]_{44}[\underline{\underline{a}}^{\sharp}(\hat{\mathbf{k}}) \cdot \operatorname{adj}(\omega^{2} \underline{\check{\rho}}^{\sharp})]\} - [\underline{\underline{a}}(\hat{\mathbf{k}})]_{41}[\underline{\underline{a}}(\hat{\mathbf{k}})]_{14}[\operatorname{adj}(\omega^{2} \underline{\check{\rho}}^{\sharp})]_{11} - [\underline{\underline{a}}(\hat{\mathbf{k}})]_{42}[\underline{\underline{a}}(\hat{\mathbf{k}})]_{24}[\operatorname{adj}(\omega^{2} \underline{\check{\rho}}^{\sharp})]_{22} - [\underline{\underline{a}}(\hat{\mathbf{k}})]_{31}[\underline{\underline{a}}(\hat{\mathbf{k}})]_{13}[\operatorname{adj}(\omega^{2} \underline{\check{\rho}}^{\sharp})]_{33})$$
(42)

with the 3 \times 3 matrixes $\underline{\underline{a}}^{\sharp}$ and $\underline{\underline{\check{\rho}}}^{\sharp}$ having entries

$$\begin{bmatrix} \underline{\mathbf{a}}^{\sharp} \end{bmatrix}_{pq} = \begin{bmatrix} \underline{\mathbf{a}}(\hat{\mathbf{k}}) \end{bmatrix}_{pq} \\ \begin{bmatrix} \underline{\check{p}}^{\sharp} \end{bmatrix}_{pq} = \begin{bmatrix} \underline{\check{p}}^{(\text{OCM})} \end{bmatrix}_{pq} \end{bmatrix} \qquad (p, q = 1, 2, 3).$$
(43)

$$p_1 = \sqrt{P_A - \frac{1}{3} \left(\frac{2^{1/3} P_B}{P_C} - \frac{P_C}{2^{1/3}}\right)},\tag{44}$$

$$p_2 = \sqrt{P_A + \frac{1}{3} \left(\frac{(1 + i\sqrt{3})P_B}{2^{2/3}P_C} - \frac{(1 - i\sqrt{3})P_C}{2^{4/3}} \right)},$$
(45)

$$p_3 = \sqrt{P_A + \frac{1}{3} \left(\frac{(1 - i\sqrt{3})P_B}{2^{2/3}P_C} - \frac{(1 + i\sqrt{3})P_C}{2^{4/3}} \right)},$$
(46)

wherein

$$P_{A} = \frac{\omega^{2} \operatorname{tr}\{\operatorname{adj}[\underline{\underline{a}}(\hat{\mathbf{k}})] \cdot \underline{\check{\rho}}^{(\operatorname{OCM})}\}}{3 \operatorname{det}[\underline{\underline{a}}(\hat{\mathbf{k}})]}, \qquad (47)$$

$$P_B = -C_A^2 + 3C_B, (48)$$

$$P_C = \left[P_D + \left(4P_B^3 + P_D^2 \right)^{1/2} \right]^{1/3}, \tag{49}$$

$$P_D = -2C_A^3 + 9C_A C_B - 27C_C, (50)$$

with

$$C_{A} = \frac{-\omega^{2} \operatorname{tr}\{\operatorname{adj}[\underline{\underline{a}}(\hat{\mathbf{k}})] \cdot \underline{\check{\rho}}^{(\operatorname{OCM})}\}}{\operatorname{det}[\underline{\underline{a}}(\hat{\mathbf{k}})]}, \qquad (51)$$

$$C_{B} = \frac{\omega^{4}}{\det[\underline{\mathbf{a}}(\hat{\mathbf{k}})]} \{ [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{44} \operatorname{tr}[\underline{\mathbf{a}}^{\sharp}(\hat{\mathbf{k}}) \cdot \operatorname{adj}(\check{\boldsymbol{\rho}}^{\sharp})] + [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{41} [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{14} [\operatorname{adj}(\check{\boldsymbol{\rho}}^{(\mathrm{OCM})})]_{11} \\ + [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{42} [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{24} [\operatorname{adj}(\check{\boldsymbol{\rho}}^{(\mathrm{OCM})})]_{22} + [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{43} [\underline{\mathbf{a}}(\hat{\mathbf{k}})]_{34} [\operatorname{adj}(\check{\boldsymbol{\rho}}^{(\mathrm{OCM})})]_{33} \}, \quad (52)$$
$$- \omega^{6} \operatorname{tr}\{\operatorname{adi}(\check{\boldsymbol{\rho}}^{(\mathrm{OCM})})] \cdot \mathbf{a}(\hat{\mathbf{k}}) \}$$

$$C_C = \frac{-\omega \operatorname{tr}\{\operatorname{adj}[\underline{p}] \to j \cdot \underline{\underline{a}}(\mathbf{k})\}}{\operatorname{det}[\underline{\underline{a}}(\hat{\mathbf{k}})]}.$$
(53)

$$\check{C}_{lMPq}^{(\text{SPFT})} = \check{C}_{lMPq}^{(\text{OCM})} + \frac{\omega^2 f^{(1)} f^{(2)}}{4\pi i} \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} d\phi \, d\theta \, \frac{k_t \sin\theta}{(k\sigma)^2 \det[\underline{\mathbf{a}}(\hat{\mathbf{k}})]} [\check{\underline{\mathbf{p}}}^{(\text{OCM})}]_{XY}[\underline{\mathbf{b}}(\hat{\mathbf{k}})]_{YU} \\
\times \left(\left\{ \xi_{lMrs}^{(2)} - \xi_{lMrs}^{(1)} \right\} \{ k_s[\underline{\mathbf{a}}^{-1}(\hat{\mathbf{k}})]_{rX} + k_r[\underline{\mathbf{a}}^{-1}(\hat{\mathbf{k}})]_{sX} \} \\
+ \left\{ \xi_{lm4s}^{(2)} - \xi_{lm4s}^{(1)} \right\} \{ k_s[\underline{\mathbf{a}}^{-1}(\hat{\mathbf{k}})]_{4X} \} \left(\xi_{tUPq}^{(2)} - \xi_{tUPq}^{(1)} \right) \tag{54}$$

and

$$\check{\rho}_{MP}^{(\text{SPFT})} = \check{\rho}_{MP}^{(\text{OCM})} - \frac{\omega^2 f^{(1)} f^{(2)} (\check{\rho}_{MS}^{(2)} - \check{\rho}_{MS}^{(1)}) (\check{\rho}_{UP}^{(2)} - \check{\rho}_{UP}^{(1)})}{2\pi i} \\ \times \int_{\phi=0}^{2\pi} \int_{\theta=0}^{\pi} d\phi \, d\theta \, \frac{\sin \theta}{\det[\underline{\hat{\mathbf{a}}}(\hat{\mathbf{k}})]} [\underline{\hat{\mathbf{b}}}(\hat{\mathbf{k}})]_{SU},$$
(55)

(1)

where the 4×4 matrix

$$\underline{\mathbf{b}}(\hat{\mathbf{k}}) = \frac{1}{2i} \left\{ \frac{e^{iL\sigma p_1} \underline{\mathbf{D}}(p_1 \underline{\mathbf{U}} \cdot \hat{\mathbf{k}})}{\sigma p_1^4 (p_1^2 - p_2^2) (p_1^2 - p_3^2)} (1 - iL\sigma p_1) - \frac{e^{iL\sigma p_2} \underline{\mathbf{D}}(p_2 \underline{\mathbf{U}} \cdot \hat{\mathbf{k}})}{\sigma p_2^4 (p_1^2 - p_2^2) (p_2^2 - p_3^2)} (1 - iL\sigma p_2) + \frac{e^{iL\sigma p_3} \underline{\mathbf{D}}(p_3 \underline{\mathbf{U}} \cdot \hat{\mathbf{k}})}{\sigma p_3^4 (p_2^2 - p_3^2) (p_1^2 - p_3^2)} (1 - iL\sigma p_3) - \frac{1}{\sigma p_1^2 p_2^2 p_3^2} \left[\underline{\mathbf{D}}(\mathbf{0}) \left(\frac{1}{p_1^2} + \frac{1}{p_2^2} + \frac{1}{p_3^2} + \frac{\sigma^2 L^2}{2} \right) + \frac{1}{2} \frac{\partial^2}{\partial k^2} \underline{\mathbf{D}}(\mathbf{0}) \right] \right\}.$$
(56)

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$$\underline{\check{\mathbf{M}}}^{(\mathrm{SPFT})} = \begin{pmatrix} (\underline{\underline{\mathbf{C}}}^{(\mathrm{SPFT})})^{\ddagger} & (\underline{\underline{\mathbf{C}}}^{(\mathrm{SPFT})})^{\ddagger} \cdot (\underline{\underline{\mathbf{e}}}^{(\mathrm{SPFT})})^{T} \\ \underline{\underline{\mathbf{e}}}^{(\mathrm{SPFT})} \cdot (\underline{\underline{\mathbf{C}}}^{(\mathrm{SPFT})})^{\ddagger} & \underline{\underline{\mathbf{e}}}^{(\mathrm{SPFT})} + \underline{\underline{\mathbf{e}}}^{(\mathrm{SPFT})} \cdot (\underline{\underline{\mathbf{C}}}^{(\mathrm{SPFT})})^{\ddagger} \cdot (\underline{\underline{\mathbf{e}}}^{(\mathrm{SPFT})})^{T} \end{pmatrix}$$
(57)

Let us note that convergence of the SPFT scheme has been demonstrated at the secondorder level of approximation for the electromagnetic constitutive parameters of a very general class of linear HCMs [22, 23]. Accordingly, we do not consider the third-order SPFT here.

3. Numerical results

3.1. Preliminaries

In order to illustrate the theory presented in section 2, let us now consider a representative numerical example. A comparison for the SPFT estimate of the HCM constitutive parameters is provided by the corresponding results computed using the Mori–Tanaka formalism [8, 11, 24, 25]. In the case of orthorhombic mm2 piezoelectric component materials, the Mori–Tanaka estimate of the extended stiffness matrix for the HCM is given by [12]

$$\underline{\underline{\check{\mathbf{C}}}}^{(\mathrm{MT})} = \underline{\underline{\check{\mathbf{C}}}}^{(1)} + f^{(2)}(\underline{\underline{\check{\mathbf{C}}}}^{(2)} - \underline{\underline{\check{\mathbf{C}}}}^{(1)}) \cdot \underline{\underline{\mathbf{B}}}^{(\mathrm{MT})} \cdot [f^{(1)}\underline{\underline{\tau}} + f^{(2)}\underline{\underline{\mathbf{B}}}^{(\mathrm{MT})}]^{\dagger},$$
(58)

where the 12×12 matrix

$$\underline{\underline{\mathbf{B}}}^{(\mathrm{MT})} = [\underline{\underline{\tau}} + \underline{\underline{\mathbf{S}}}^{(\mathrm{Esh})} \cdot (\underline{\underline{\check{\mathbf{C}}}}^{(1)})^{\dagger} \cdot (\underline{\underline{\check{\mathbf{C}}}}^{(2)} - \underline{\underline{\check{\mathbf{C}}}}^{(1)})]^{\dagger}$$
(59)

∿

္

 $C_{1212} \equiv C_{66}$

Stiffness parameter PVDF (GPa) LaRC-SI (GPa) $C_{1111} \equiv C_{11}$ 3.8 8.1 $C_{1122} \equiv C_{12}$ $C_{1133} \equiv C_{13}$ 1.9 5.4 1.0 5.4 $C_{2222} \equiv C_{22}$ 3.2 8.1 $C_{2233} \equiv C_{23}$ 0.9 5.4 $C_{3333} \equiv C_{33}$ 1.2 8.1 $C_{2323} \equiv C_{44}$ 0.7 1.4 $C_{1313} \equiv C_{55}$ 0.9 1.4

0.9

Table 1. The stiffness constitutive parameters of the component materials in units of GPa (after [12]).

1.4

3.2. Lowest order SPFT

္) or operating in the secter of the secter of

$$\lim_{f^{(2)}\to 0} \underline{\check{\mathbf{C}}}^{(\mathrm{HCM})} = \underline{\check{\mathbf{C}}}^{(1)}, \qquad \lim_{f^{(2)}\to 1} \underline{\check{\mathbf{C}}}^{(\mathrm{HCM})} = \underline{\check{\mathbf{C}}}^{(2)}.$$
(60)

3.3. Second-order SPFT estimate

Now let us turn to the second-order SPFT estimates of the HCM constitutive parameters. We considered these quantities as functions of $\bar{k}L$, where \bar{k} is an approximate upper bound on the



Figure 2. Plots of $[\underline{\check{C}}^{(HCM)}]_{1,1}$ (in GPa), $[\underline{\check{C}}^{(HCM)}]_{1,12}$ (in C m⁻²) and $(1/\epsilon_0)[\underline{\check{C}}^{(hcm)}]_{12,12}$ as estimated using the lowest order SPFT (i.e., HCM = OCM) (black, dashed curves) and the Mori–Tanaka formalism (i.e., HCM = MT) (red, solid curves) versus the volume fraction of component material '2'. Component material '1' is PVDF and component material '2' is LaRC-SI, as described in section 3.1. The component materials are distributed as spheres (i.e., a = b = c).

wavenumbers supported by the HCM, as estimated by [19]

$$\bar{k} = \frac{\omega}{2} \left(\sqrt{\frac{\bar{\rho}}{\bar{\lambda} + 2\bar{\mu}}} + \sqrt{\frac{\bar{\rho}}{\bar{\mu}}} \right),\tag{61}$$



Figure 3. As figure 2 but with the component materials distributed as ellipsoids with (a/c = 5 and b/c = 1.5).

wherein

$$\begin{split} \bar{\lambda} &= \frac{1}{6} \sum_{\ell=1}^{2} (|[\underline{\underline{C}}^{(\ell)}]_{12}| + |[\underline{\underline{C}}^{(\ell)}]_{13}| + |[\underline{\underline{C}}^{(\ell)}]_{23}|) \\ \bar{\mu} &= \frac{1}{6} \sum_{\ell=1}^{2} (|[\underline{\underline{C}}^{(\ell)}]_{44}| + |[\underline{\underline{C}}^{(\ell)}]_{55}| + |[\underline{\underline{C}}^{(\ell)}]_{66}|) \\ \bar{\rho} &= \frac{1}{2} \sum_{\ell=1}^{2} \rho^{(\ell)} \end{split}$$
(62)



Figure 4. As figure 2 but with the component materials distributed as ellipsoids with (a/c = 10 and b/c = 2).



Figure 5. Plots of the real and imaginary parts of the second-order SPFT estimates $[\underline{\underline{C}}^{(\text{SPFT})}]_{1,1}$ (in GPa), $[\underline{\underline{C}}^{(\text{SPFT})}]_{1,12}$ (in C m⁻²) and $(10^3/\epsilon_0)[\underline{\underline{C}}^{(\text{SPFT})}]_{12,12}$, where $\underline{\underline{C}}^{(\text{SPFT})} = \underline{\underline{C}}^{(\text{SPFT})} - \underline{\underline{C}}^{(\text{OCM})}$, versus $\overline{k}L$, with $f^{(2)} = 0.5$. The results from the spherical particle (i.e., a = b = c = 1) case (red, solid line) are plotted alongside the cases with elliptical particles with a = 5, b = 1.5, c = 1 (blue, short-dashed line) and a = 10, b = 2, c = 1 (black, long-dashed line).



Figure 6. As figure 5 but with the real and imaginary parts of $[\underline{\tilde{\rho}}^{(\text{SPFT})}]_{11}$ (in kg m⁻³), where $\underline{\tilde{\rho}}^{(\text{SPFT})} = \underline{\tilde{\rho}}^{(\text{SPFT})} - \underline{\tilde{\rho}}^{(\text{OCM})}$, plotted as functions of $\bar{k}L$, with $f^{(2)} = 0.5$.

∿

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4. Closing remarks

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From our theoretical considerations and representative numerical studies, the following conclusions were drawn.

- The lowest order SPFT estimate of the stiffness, piezoelectric and dielectric properties of the HCM are qualitatively similar to those estimates provided by the Mori–Tanaka formalism.
- Differences between the estimates of the lowest order SPFT and the Mori–Tanaka formalism are greatest at mid-range values of the volume fraction, and accentuated when the component particles are eccentric in shape.
- The second-order SPFT provides a correction to the lowest order estimate of the HCM constitutive properties. The magnitude of this correction is generally larger when the component particles are more eccentric in shape and vanishes as the correlation length tends to zero.
- While the correction provided by the second-order SPFT is relatively small in magnitude, it is highly significant as it indicates attenuation due to scattering loss.

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Appendix A

The extended symbol \check{A}_{aMPq} $(a, q \in \{1, 2, 3\}, M, P \in \{1, 2, 3, 4\})$ may be conveniently represented by the 12×12 matrix with entries $[\underline{\check{A}}]_{\gamma\kappa}$ $(\gamma, \kappa \in [1, 12])$, upon replacing the index pair aM with γ and the index pair Pq with κ . For the most general 12×12 matrix encountered in this paper, which has the form

	$(A_{1,1})$	$A_{1,2}$	$A_{1,3}$	0	0	0	0	0	0	0	0	$A_{1,12}$	
Ă <u>=</u>	$A_{2,1}$	$A_{2,2}$	$A_{2,3}$	0	0	0	0	0	0	0	0	$A_{2,12}$	
	$A_{3,1}$	$A_{3,2}$	$A_{3,3}$	0	0	0	0	0	0	0	0	$A_{3,12}$	
	0	0	0	$A_{4,4}$	0	0	$A_{4,4}$	0	0	0	$A_{4,11}$	0	
	0	0	0	0	$A_{5,5}$	0	0	$A_{5,5}$	0	$A_{5,10}$	0	0	
	0	0	0	0	0	$A_{6,6}$	0	0	$A_{6,6}$	0	0	0	
	0	0	0	$A_{4,4}$	0	0	$A_{4,4}$	0	0	0	$A_{4,11}$	0	,
	0	0	0	0	$A_{5,5}$	0	0	$A_{5,5}$	0	$A_{5,10}$	0	0	
	0	0	0	0	0	$A_{6,6}$	0	0	$A_{6,6}$	0	0	0	
	0	0	0	0	$A_{10,5}$	0	0	$A_{10,5}$	0	$A_{10,10}$	0	0	
	0	0	0	$A_{11,4}$	0	0	$A_{11,4}$	0	0	0	$A_{11,11}$	0	
	$A_{12,1}$	$A_{12,2}$	$A_{12,3}$	0	0	0	0	0	0	0	0	$A_{12,12}$	
												(A.	1)

the correspondence between the extended symbol indexes and the matrix indexes is provided in table A.1. The scheme presented in table A.1 also relates the extended symbol \check{t}_{aM} to the corresponding column 12-vector entries $[\check{t}]_{\gamma}$.

ੌ									
aM or Pq	γ or κ	პ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ კ	γ or κ	َ	γ or κ	னனனை இன்றனை இன்றனனை இன்றனனஇன்றனை இன்றனை இன்றன இன்றன் இன்றனை இன்றன இன்றன் இன்றனை இன்றன் இன்றன் இன்றன் இன்றன் இன்றன் இன்றனை இன்றனை இன்றனை இன்றன	γ or κ		
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33	3	സസസസസസസസസസസസസസസസസസസസസസസസസസസം,	6	ه المع المع المع المع المع المع المع المع	9	Έμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμμ	12		

 Table A.1. Conversion between the extended symbol and matrix notation.

We introduce the matrix $\underline{\check{A}}^\dagger$ which plays a role similar to the matrix inverse insofar as

$$\underline{\check{\mathbf{A}}}^{\dagger} \cdot \underline{\check{\mathbf{A}}} = \underline{\check{\mathbf{A}}} \cdot \underline{\check{\mathbf{A}}}^{\dagger} = \underline{\underline{\tau}}. \tag{A.2}$$

Herein,

$$\underline{\tau} = \begin{pmatrix} \mathbf{I} & \underline{\mathbf{0}}_{3\times3} & \underline{\mathbf{0}}_{3\times3} & \underline{\mathbf{0}}_{3\times3} & \underline{\mathbf{0}}_{3\times3} \\ \underline{\mathbf{0}}_{3\times3} & \frac{1}{2}\mathbf{I} & \frac{1}{2}\mathbf{I} & \underline{\mathbf{0}}_{3\times3} \\ \underline{\mathbf{0}}_{3\times3} & \frac{1}{2}\mathbf{I} & \frac{1}{2}\mathbf{I} & \underline{\mathbf{0}}_{3\times3} \\ \underline{\mathbf{0}}_{3\times3} & \underline{\mathbf{0}}_{3\times3} & \underline{\mathbf{0}}_{3\times3} & \mathbf{I} \\ \end{bmatrix}$$
(A.3)

∿

$$\underline{\check{\underline{A}}} \cdot \underline{\underline{\tau}} = \underline{\underline{\tau}} \cdot \underline{\check{\underline{A}}} = \underline{\check{\underline{A}}}.$$
(A.4)

The matrix $\underline{\breve{A}}^{\dagger}$ has the form

	(†1,1	†1,2	†1,3	0	0	0	0	0	0	0	0	†1,12	
$\check{\underline{\mathbf{A}}}^{\dagger} =$	†2,1	†2,2	†2,3	0	0	0	0	0	0	0	0	†2,12	
	†3,1	†3,2	†3,3	0	0	0	0	0	0	0	0	†3,12	
	0	0	0	$\frac{\frac{1}{4,4}}{2}$	0	0	$\frac{^{\dagger}4,4}{2}$	0	0	0	[†] 4,11	0	
	0	0	0	0	$\frac{1}{2}$	0	0	$\frac{1}{2}$	0	†5,10	0	0	
	0	0	0	0	0	$\frac{\dagger_{6,6}}{2}$	0	0	$\frac{\dagger_{6,6}}{2}$	0	0	0	
	0	0	0	$\frac{\dagger_{4,4}}{2}$	0	Ō	$\frac{^{\dagger}4,4}{2}$	0	0	0	†4,11	0	,
	0	0	0	Ō	$\frac{1}{2}$	0	Ō	$\frac{1}{2}$	0	†5,10	0	0	
	0	0	0	0	Ō	$\frac{\frac{1}{6,6}}{2}$	0	Ō	$\frac{1}{6,6}$	0	0	0	
	0	0	0	0	†10,5	Ō	0	†10,5	Ō	†10,10	0	0	
	0	0	0	†11,4	0	0	†11,4	0	0	0	†11,11	0	
	(†12,1	†12,2	†12,3	0	0	0	0	0	0	0	0	†12,12 /	
												(A	

with entries

$$\dagger_{1,2} = (A_{1,2}A_{12,3}A_{3,12} - A_{12,2}A_{1,3}A_{3,12} - A_{1,12}A_{12,3}A_{3,2} + A_{12,12}A_{1,3}A_{3,2} - A_{1,2}A_{12,12}A_{3,3} + A_{1,12}A_{12,2}A_{3,3})/\Lambda,$$
(A.7)

$$\begin{aligned} \dagger_{1,3} &= (-A_{1,2}A_{12,3}A_{2,12} + A_{12,2}A_{1,3}A_{2,12} + A_{1,12}A_{12,3}A_{2,2} - A_{12,12}A_{1,3}A_{2,2} \\ &+ A_{1,2}A_{12,12}A_{2,3} - A_{1,12}A_{12,2}A_{2,3})/\Lambda, \end{aligned}$$
(A.8)

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cheres and a series	(A.26)

$$\begin{aligned}
^{\dagger}_{12,2} &= (-A_{1,2}A_{12,3}A_{3,1} + A_{12,2}A_{1,3}A_{3,1} + A_{1,1}A_{12,3}A_{3,2} - A_{12,1}A_{1,3}A_{3,2} \\
&+ A_{1,2}A_{12,1}A_{3,3} - A_{1,1}A_{12,2}A_{3,3})/\Lambda, \\
^{\dagger}_{12,3} &= (A_{1,2}A_{12,3}A_{2,1} - A_{12,2}A_{1,3}A_{2,1} - A_{1,1}A_{12,3}A_{2,2} + A_{12,1}A_{1,3}A_{2,2} \\
&- A_{1,2}A_{12,1}A_{2,3} + A_{1,1}A_{12,2}A_{2,3})/\Lambda,
\end{aligned}$$
(A.27)

$$\dagger_{11,4} = \frac{A_{11,4}}{2(A_{11,4}A_{4,11} - A_{11,11}A_{4,4})},\tag{A.29}$$

$$\dagger_{10,5} = \frac{A_{10,5}}{2(A_{10,5}A_{5,10} - A_{10,10}A_{5,5})},\tag{A.30}$$

where the scalar

$$\begin{split} \Lambda &= A_{1,12}A_{12,3}A_{2,2}A_{3,1} - A_{12,12}A_{1,3}A_{2,2}A_{3,1} - A_{1,1}A_{12,3}A_{2,2}A_{3,12} + A_{12,1}A_{1,3}A_{2,2}A_{3,12} \\ &\quad -A_{1,12}A_{12,3}A_{2,1}A_{3,2} + A_{12,12}A_{1,3}A_{2,1}A_{3,2} + A_{1,1}A_{12,3}A_{2,12}A_{3,2} \\ &\quad -A_{12,1}A_{1,3}A_{2,12}A_{3,2} + A_{1,12}A_{12,1}A_{2,3}A_{3,2} - A_{1,1}A_{12,12}A_{2,3}A_{3,2} \\ &\quad -A_{1,12}A_{12,1}A_{2,2}A_{3,3} + A_{1,1}A_{12,12}A_{2,2}A_{3,3} + A_{12,2}(A_{1,3}A_{2,12}A_{3,1}) \\ &\quad -A_{1,12}A_{2,3}A_{3,1} - A_{1,3}A_{2,1}A_{3,12} + A_{1,1}A_{2,3}A_{3,12} + A_{1,12}A_{2,1}A_{3,3} \\ &\quad -A_{1,1}A_{2,12}A_{3,3}) + A_{1,2}(-A_{12,3}A_{2,12}A_{3,1} + A_{12,12}A_{2,3}A_{3,1} + A_{12,3}A_{2,1}A_{3,12} \\ &\quad -A_{12,1}A_{2,3}A_{3,12} - A_{12,12}A_{2,1}A_{3,3} + A_{12,1}A_{2,12}A_{3,3}). \end{split}$$

Appendix **B**

The extended Eshelby symbol appropriate to orthorhombic mm2 piezoelectric materials, distributed as ellipsoidal particles with shape parameters $\{a, b, c\}$, is given by [9, 34]

$$S_{MnAb}^{(\text{Esh})} = \begin{cases} \frac{1}{8\pi} C_{sJAb}^{(1)} \int_{-1}^{+1} d\zeta_3 \int_{0}^{2\pi} d\omega [F_{mJsn}(\overline{\vartheta}) + F_{nJsm}(\overline{\vartheta})], & M = m = 1, 2, 3\\ \frac{1}{4\pi} C_{sJAb}^{(1)} \int_{-1}^{+1} d\zeta_3 \int_{0}^{2\pi} d\omega F_{4Jsn}(\overline{\vartheta}), & M = 4, \end{cases}$$
(B.1)

wherein

$$F_{MJsn}(\overline{\vartheta}) = \overline{\vartheta}_s \overline{\vartheta}_n K_{MJ}^{-1}, \qquad K_{JR} = \overline{\vartheta}_s C_{sJRn}^{(1)} \overline{\vartheta}_n \overline{\vartheta}_1 = \frac{\zeta_1}{a}, \qquad \overline{\vartheta}_2 = \frac{\zeta_2}{b}, \qquad \overline{\vartheta}_3 = \frac{\zeta_3}{c} \zeta_1 = \left(1 - \zeta_3^2\right)^{1/2} \cos(\omega), \qquad \zeta_2 = \left(1 - \zeta_3^2\right)^{1/2} \sin(\omega), \qquad \zeta_3 = \zeta_3$$
(B.2)

The integrals in equations (B.1) can be evaluated using standard numerical methods [32]. The conversion from the extended Eshelby symbol $S_{MnAb}^{(Esh)}$ to the extended Eshelby 12 × 12 matrix, namely $\underline{\underline{S}}^{(Esh)}$, follows the scheme described in appendix A.

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